INTEGRATED CIRCUITS

DATA SHEET



PCA9545

4-channel I²C switch with interrupt logic and reset

Product data sheet Supersedes data of 2002 Dec 13





4-channel I²C switch with interrupt logic and reset

PCA9545



FEATURES

- 1-of-4 bi-directional translating switches
- I²C interface logic; compatible with SMBus standards
- 4 active LOW interrupt inputs
- Active LOW interrupt output
- Active LOW reset input
- 2 address pins allowing up to 4 devices on the I²C-bus
- Channel selection via I²C-bus, in any combination
- Power up with all switch channels deselected
- Low RDS_{ON} switches
- Allows voltage level translation between 1.8 V, 2.5 V, 3.3 V and 5 V buses
- No glitch on power-up
- Supports hot insertion
- Low stand-by current
- Operating power supply voltage range of 2.3 V to 5.5 V
- 5 V tolerant Inputs
- 0 kHz to 400 kHz clock frequency
- ESD protection exceeds 2000 V HBM per JESD22-A114, 150 V MM per JESD22-A115 and 1000 V per JESD22-C101
- Latch-up testing is done to JESDEC Standard JESD78 which exceeds 100 mA
- Three packages offered: SO20, TSSOP20, and HVQFN20

DESCRIPTION

The PCA9545 is a quad bi-directional translating switch controlled via the I²C-bus. The SCL/SDA upstream pair fans out to four downstream pairs, or channels. Any individual SCx/SDx channel or combination of channels can be selected, determined by the contents of the programmable control register. Four interrupt inputs, $\overline{\text{INT0}}$ to $\overline{\text{INT3}}$, one for each of the downstream pairs, are provided. One interrupt output, $\overline{\text{INT}}$, acts as an AND of the four interrupt inputs.

An active-LOW reset input allows the PCA9545 to recover from a situation where one of the downstream I^2C -buses is stuck in a LOW state. Pulling the RESET pin LOW resets the I^2C state machine and causes all the channels to be deselected as does the internal power on reset function.

The pass gates of the switches are constructed such that the V_{DD} pin can be used to limit the maximum high voltage which will be passed by the PCA9545. This allows the use of different bus voltages on each pair, so that 1.8 V or 2.5 V or 3.3 V parts can communicate with 5 V parts without any additional protection. External pull-up resistors pull the bus up to the desired voltage level for each channel. All I/O pins are 5 V tolerant.

ORDERING INFORMATION

PACKAGES	TEMPERATURE RANGE	ORDER CODE	DRAWING NUMBER
20-Pin Plastic SO	−40 °C to +85 °C	PCA9545D	SOT163-1
20-Pin Plastic TSSOP	−40 °C to +85 °C	PCA9545PW	SOT360-1
20-Pin Plastic HVQFN	−40 °C to +85 °C	PCA9545BS	SOT662-1

Standard packing quantities and other packaging data are available at www.standardproducts.philips.com/packaging.

4-channel I²C switch with interrupt logic and reset

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${\bf PIN~CONFIGURATION-SO,~TSSOP}$

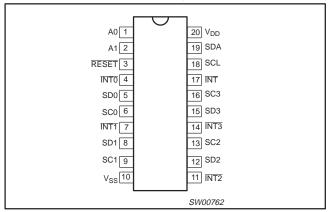


Figure 1. Pin configuration — SO, TSSOP

PIN CONFIGURATION — HVQFN

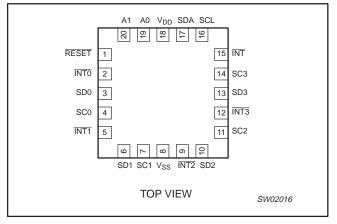


Figure 2. Pin configuration — HVQFN

PIN DESCRIPTION

SO, TSSOP PIN NUMBER	HVQFN PIN NUMBER	SYMBOL	FUNCTION
1	19	A0	Address input 0
2	20	A1	Address input 1
3	1	RESET	Active LOW reset input
4	2	ĪNT0	Active LOW interrupt input 0
5	3	SD0	Serial data 0
6	4	SC0	Serial clock 0
7	5	ĪNT1	Active LOW interrupt input 1
8	6	SD1	Serial data 1
9	7	SC1	Serial clock 1
10	8	V _{SS}	Supply ground
11	9	ĪNT2	Active LOW interrupt input 2
12	10	SD2	Serial data 2
13	11	SC2	Serial clock 2
14	12	ĪNT3	Active LOW interrupt input 3
15	13	SD3	Serial data 3
16	14	SC3	Serial clock 3
17	15	ĪNT	Active LOW interrupt output
18	16	SCL	Serial clock line
19	17	SDA	Serial data line
20	18	V_{DD}	Supply voltage

4-channel I²C switch with interrupt logic and reset

PCA9545

BLOCK DIAGRAM

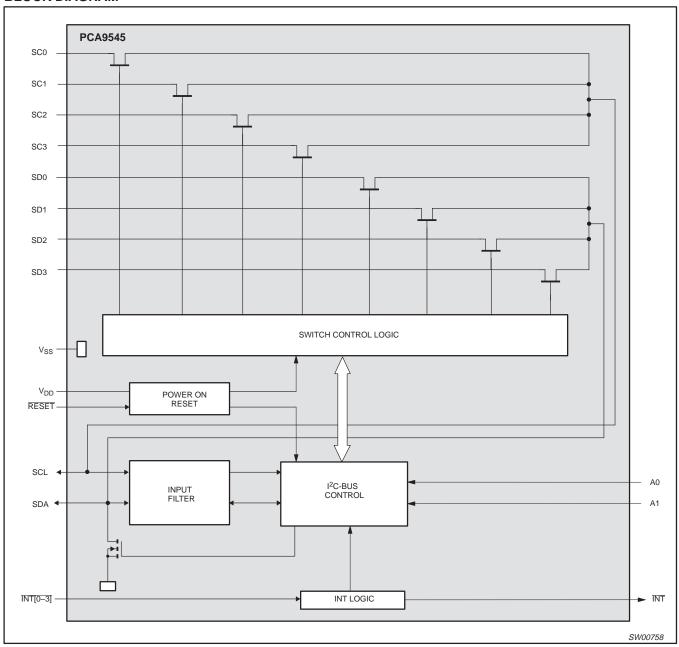


Figure 3. Block diagram

4-channel I²C switch with interrupt logic and reset

PCA9545

DEVICE ADDRESS

Following a START condition the bus master must output the address of the slave it is accessing. The address of the PCA9545 is shown in Figure 4. To conserve power, no internal pullup resistors are incorporated on the hardware selectable address pins and they must be pulled HIGH or LOW.

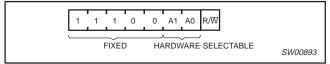


Figure 4. Slave address

The last bit of the slave address defines the operation to be performed. When set to logic 1, a read is selected while a logic 0 selects a write operation.

CONTROL REGISTER

Following the successful acknowledgement of the slave address, the bus master will send a byte to the PCA9545, which will be stored in the control register. If multiple bytes are received by the PCA9545, it will save the last byte received. This register can be written and read via the I²C-bus.

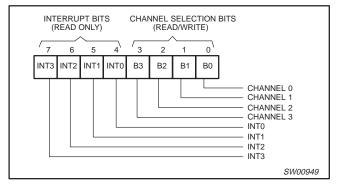


Figure 5. Control Register

CONTROL REGISTER DEFINITION

One or several SCx/SDx downstream pair, or channel, is selected by the contents of the control register. This register is written after the PCA9545 has been addressed. The 2 LSBs of the control byte are used to determine which channel is to be selected. When a channel is selected, the channel will become active after a stop condition has been placed on the I²C-bus. This ensures that all SCx/SDx lines will be in a HIGH state when the channel is made active, so that no false conditions are generated at the time of connection.

Table 1. Control Register; Write — Channel Selection/ Read — Channel Status

INT3	INT2	INT1	INT0	В3	B2	B1	В0	COMMAND
Х	Х	Х	Х	Х	Х	Х	0	Channel 0 disabled
^	^	^	^	^	^	^	1	Channel 0 enabled
Х	Х	Х	Х	Х	Х	0	Х	Channel 1 disabled
<	^	^	^	Х	^	1	^	Channel 1 enabled
Х	x	Х	0	Х	Х	Channel 2 disabled		
^	^	^	^	^	1	^	^	Channel 2 enabled
Х	Х	Х	Х	1	Х	Х	Х	Channel 3 disabled
^	^	^	^		^	^	^	Channel 3 enabled
0	0	0	0	0	0	0	0	No channel selected; power-up/ reset default state

NOTE: Several channels can be enabled at the same time. Ex: B3 = 0, B2 = 1, B1 = 1, B0 = 0, means that channel 0 and 3 are disabled and channel 1 and 2 are enabled.

Care should be taken not to exceed the maximum bus capacity.

4-channel I²C switch with interrupt logic and reset

PCA9545

INTERRUPT HANDLING

The PCA9545 provides 4 interrupt inputs, one for each channel, and one open drain interrupt output. When an interrupt is generated by any device, it will be detected by the PCA9545 and the interrupt output will be driven LOW. The channel does not need to be active for detection of the interrupt. A bit is also set in the control register.

Bits 4-7 of the control register correspond to channels 0-3 of the PCA9545, respectively. Therefore, if an interrupt is generated by any device connected to channel 1, the state of the interrupt inputs is loaded into the control register when a read is accomplished. Likewise, an interrupt on any device connected to channel 0 would cause bit 4 of the control register to be set on the read. The master can then address the PCA9545 and read the contents of the control register to determine which channel contains the device generating the interrupt. The master can then reconfigure the PCA9545 to select this channel, and locate the device generating the interrupt and clear it.

It should be noted that more than one device can be providing an interrupt on a channel, so it is up to the master to ensure that all devices on a channel are interrogated for an interrupt.

The interrupt inputs may be used as general purpose inputs if the interrupt function is not required.

If unused, interrupt input(s) must be connected to $V_{\mbox{\scriptsize DD}}$ through a pull-up resistor.

Table 2. Control Register Read — Interrupt

			_			•													
INT3	INT2	INT1	INT0	В3	B2	B1	B0	COMMAND											
×	х	Х	0	Х	Х	х	Х	No interrupt on channel 0											
	^	^	1	^		^	^	Interrupt on channel 0											
×	х	0	×	х	Х	Х	X	No interrupt on channel 1											
	^ ^	1	<u> </u>		^	^	^	Interrupt on channel 1											
×	0	×	X	Х	х	X	X	No interrupt on channel 2											
	1	^	^	^		^	^	Interrupt on channel 2											
0	Y	Х	X	х	Х	X	Х	No interrupt on channel 3											
1)	Х	X	X	×	X	X	×	Х	X	Х	Х	Х			^		^	*	Interrupt on channel 3

NOTE: Several interrupts can be active at the same time. Ex: INT3 = 0, INT2 = 1, INT1 = 1, INT0 = 0, means that there is no interrupt on channels 0 and 3, and there is interrupt on channels 1 and 2.

RESET INPUT

The RESET input is an active-LOW signal which may be used to recover from a bus fault condition. By asserting this signal LOW for a minimum of t_{WL} , the PCA9545 will reset its registers and I^2C state machine and will deselect all channels. The RESET input must be connected to V_{DD} through a pull-up resistor.

POWER-ON RESET

When power is applied to V_{DD} , an internal Power On Reset holds the PCA9545 in a reset state until V_{DD} has reached V_{POR} . At this point, the reset condition is released and the PCA9545 registers and I^2C state machine are initialized to their default states, all zeroes causing all the channels to be deselected.

VOLTAGE TRANSLATION

The pass gate transistors of the PCA9545 are constructed such that the V_{DD} voltage can be used to limit the maximum voltage that will be passed from one I²C-bus to another.

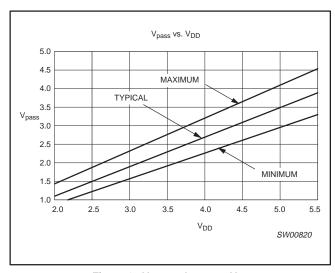


Figure 6. V_{pass} voltage vs. V_{DD}

Figure 6 shows the voltage characteristics of the pass gate transistors (note that the graph was generated using the data specified in the DC Characteristics section of this datasheet). In order for the PCA9545 to act as a voltage translator, the V_{pass} voltage should be equal to, or lower than the lowest bus voltage. For example, if the main bus was running at 5 V, and the downstream buses were 3.3 V and 2.7 V, then V_{pass} should be equal to or below 2.7 V to effectively clamp the downstream bus voltages. Looking at Figure 6, we see that V_{pass} (max.) will be at 2.7 V when the PCA9545 supply voltage is 3.5 V or lower so the PCA9545 supply voltage could be set to 3.3 V. Pull-up resistors can then be used to bring the bus voltages to their appropriate levels (see Figure 13).

More Information can be found in Application Note AN262 *PCA954X* family of I²C/SMBus multiplexers and switches.

4-channel I²C switch with interrupt logic and reset

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CHARACTERISTICS OF THE I2C-BUS

The I²C-bus is for 2-way, 2-line communication between different ICs or modules. The two lines are a serial data line (SDA) and a serial clock line (SCL). Both lines must be connected to a positive supply via a pull-up resistor when connected to the output stages of a device. Data transfer may be initiated only when the bus is not busy.

Bit transfer

One data bit is transferred during each clock pulse. The data on the SDA line must remain stable during the HIGH period of the clock pulse as changes in the data line at this time will be interpreted as control signals (see Figure 7).

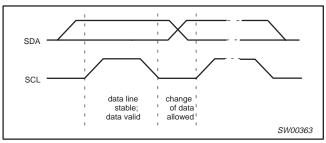


Figure 7. Bit transfer

Start and stop conditions

Both data and clock lines remain HIGH when the bus is not busy. A HIGH-to-LOW transition of the data line, while the clock is HIGH is defined as the start condition (S). A LOW-to-HIGH transition of the data line while the clock is HIGH is defined as the stop condition (P) (see Figure 8).

System configuration

A device generating a message is a 'transmitter', a device receiving is the 'receiver'. The device that controls the message is the 'master' and the devices which are controlled by the master are the 'slaves' (see Figure 9).

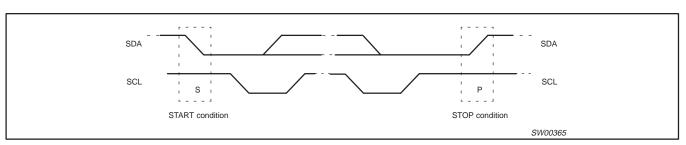


Figure 8. Definition of start and stop conditions

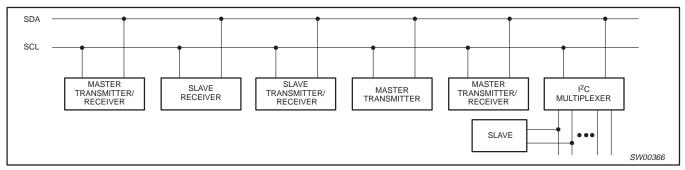


Figure 9. System configuration

4-channel I²C switch with interrupt logic and reset

PCA9545

Acknowledge

The number of data bytes transferred between the start and the stop conditions from transmitter to receiver is not limited. Each byte of eight bits is followed by one acknowledge bit. The acknowledge bit is a HIGH level put on the bus by the transmitter whereas the master generates an extra acknowledge related clock pulse.

A slave receiver which is addressed must generate an acknowledge after the reception of each byte. Also a master must generate an acknowledge after the reception of each byte that has been clocked out of the slave transmitter. The device that acknowledges has to pull down the SDA line during the acknowledge clock pulse, so that the SDA line is stable LOW during the HIGH period of the acknowledge related clock pulse, set-up and hold times must be taken into account.

A master receiver must signal an end of data to the transmitter by not generating an acknowledge on the last byte that has been clocked out of the slave. In this event, the transmitter must leave the data line HIGH to enable the master to generate a stop condition.

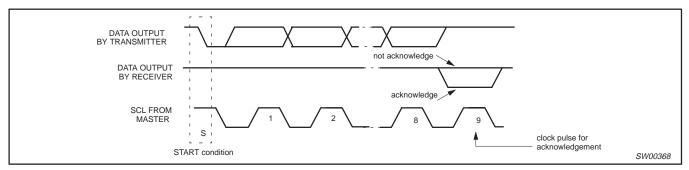


Figure 10. Acknowledgement on the I²C-bus

Bus transactions

Data is transmitted to the PCA9545 control register using the write mode as shown in Figure 11.

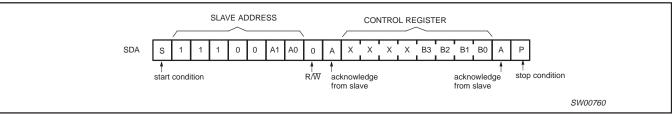


Figure 11. WRITE control register

Data is read from PCA9545 control register using the read mode as shown in Figure 12.

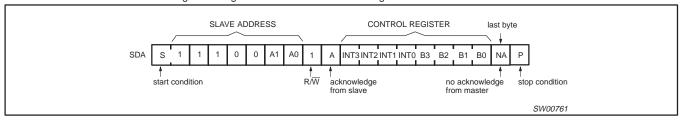


Figure 12. READ control register

4-channel I²C switch with interrupt logic and reset

PCA9545

TYPICAL APPLICATION

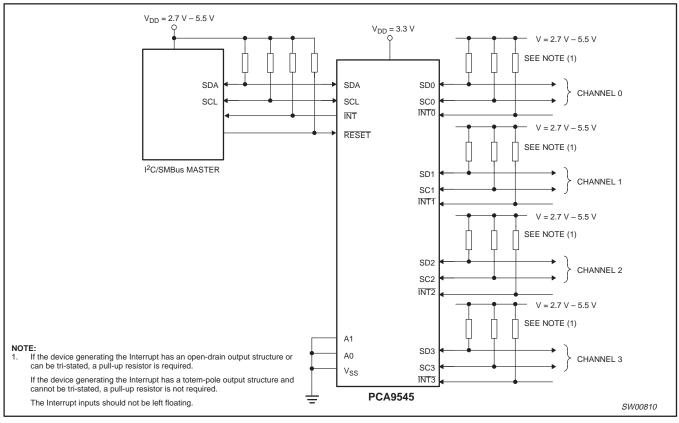


Figure 13. Typical application

ABSOLUTE MAXIMUM RATINGS^{1, 2}

In accordance with the Absolute Maximum Rating System (IEC 134). Voltages are referenced to GND (ground = 0 V).

SYMBOL	PARAMETER	CONDITIONS	RAT	UNIT	
STWIBOL	PARAMETER	CONDITIONS	MIN	MAX	UNII
V_{DD}	DC supply voltage		-0.5	+7.0	V
V _I	DC input voltage		-0.5	+7.0	V
l _l	DC input current		_	±20	mA
I _O	DC output current		_	±25	mA
I _{DD}	DC Supply current		_	±100	mA
I _{SS}	DC Supply current		_	±100	mA
P _{tot}	total power dissipation		_	400	mW
T _{stg}	Storage temperature range		-60	+150	°C
T _{amb}	Operating ambient temperature		-40	+85	°C

NOTES:

- 1. Stresses beyond those listed may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- 2. The performance capability of a high-performance integrated circuit in conjunction with its thermal environment can create junction temperatures which are detrimental to reliability. The maximum junction temperature of this integrated circuit should not exceed 150 °C.

4-channel I^2C switch with interrupt logic and reset

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DC CHARACTERISTICS

 $\underline{\text{V}_{DD}}$ = 2.3 V to 3.6 V; V_{SS} = 0 V; T_{amb} = -40 $^{\circ}\text{C}$ to +85 $^{\circ}\text{C}$; unless otherwise specified. (See page 11 for V_{DD} = 3.6 V to 5.5 V.)

0)////00/	DADAMETED	TEGT COMPLETIONS		LIMITS		LINUT
SYMBOL	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Supply						
V _{DD}	Supply voltage		2.3	_	3.6	V
I _{DD}	Supply current	Operating mode; $V_{DD} = 3.6 \text{ V}$; no load; $V_{I} = V_{DD}$ or V_{SS} ; $f_{SCL} = 100 \text{ kHz}$	_	30	100	μΑ
I _{stb}	Standby current	Standby mode; $V_{DD} = 3.6 \text{ V}$; no load; $V_{I} = V_{DD}$ or V_{SS}	_	20	100	μΑ
V _{POR}	Power-on reset voltage	no load; V _I = V _{DD} or V _{SS}	_	1.6	2.1	V
Input SCL;	input/output SDA			•	•	
V _{IL}	LOW-level input voltage		-0.5	_	0.3V _{DD}	V
V _{IH}	HIGH-level input voltage		0.7V _{DD}	<u> </u>	6	V
	LOW level systems surrent	V _{OL} = 0.4 V	3	<u> </u>	_	A
l _{OL}	LOW-level output current	V _{OL} = 0.6 V	6	_	_	mA
ΙL	Leakage current	$V_{I} = V_{DD}$ or V_{SS}	-1	<u> </u>	+1	μΑ
Ci	Input capacitance	$V_I = V_{SS}$	_	12	13	pF
Select inpu	ts A0 to A1 / INT0 to INT3 / RE	SET				-
V _{IL}	LOW-level input voltage		-0.5	_	+0.3V _{DD}	V
V _{IH}	HIGH-level input voltage		0.7V _{DD}	_	V _{DD} + 0.5	V
ILI	Input leakage current	pin at V _{DD} or V _{SS}	-1	_	+1	μΑ
Ci	Input capacitance	$V_I = V_{SS}$	_	1.6	3	pF
Pass Gate						
D	Conitab posiatores	$V_{DD} = 3.0 \text{ V to } 3.6 \text{ V}; V_{O} = 0.4 \text{ V}; I_{O} = 15 \text{ mA}$	5	20	30	0
R _{ON}	Switch resistance	$V_{DD} = 2.3 \text{ V to } 2.7 \text{ V; } V_{O} = 0.4 \text{ V; } I_{O} = 10 \text{ mA}$	7	26	55	Ω
		$V_{swin} = V_{DD} = 3.3 \text{ V}; I_{swout} = -100 \mu\text{A}$	_	2.2	_	
\/	Curitah autout valtaga	$V_{swin} = V_{DD} = 3.0 \text{ V to } 3.6 \text{ V; } I_{swout} = -100 \mu\text{A}$	1.6	_	2.8	V
V_{Pass}	Switch output voltage	$V_{swin} = V_{DD} = 2.5 \text{ V}; I_{swout} = -100 \mu\text{A}$	_	1.5	_	l v
		$V_{swin} = V_{DD} = 2.3 \text{ V to } 2.7 \text{ V; } I_{swout} = -100 \mu\text{A}$	1.1	_	2.0	
ΙL	Leakage current	$V_I = V_{DD}$ or V_{SS}	-1	_	+1	μΑ
C _{io}	Input/output capacitance	$V_I = V_{SS}$	_	3	5	pF
INT Output						
I_{OL}	LOW-level output current	V _{OL} = 0.4 V	3	_		mA
I _{OH}	HIGH-level output current		_	_	+100	μΑ

4-channel I²C switch with interrupt logic and reset

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DC CHARACTERISTICS

 $V_{DD} = 3.6 \text{ V to } 5.5 \text{ V; } V_{SS} = 0 \text{ V; } T_{amb} = -40 \text{ °C to } +85 \text{ °C; unless otherwise specified.} \text{ (See page 10 for } V_{DD} = 2.3 \text{ V to } 3.6 \text{ V.)}$

OVMDOL	DADAMETED	TEST COMPLETIONS		LIMITS		
SYMBOL	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Supply						
V_{DD}	Supply voltage		3.6	_	5.5	V
I _{DD}	Supply current	Operating mode; V_{DD} = 5.5 V; no load; V_{I} = V_{DD} or V_{SS} ; f_{SCL} = 100 kHz	_	575	600	μА
I _{stb}	Standby current	Standby mode; V_{DD} = 5.5 V; no load; V_{I} = V_{DD} or V_{SS}	_	130	200	μΑ
V _{POR}	Power-on reset voltage	no load; V _I = V _{DD} or V _{SS}	_	1.6	2.1	V
Input SCL;	input/output SDA	•	-	•	-	
V _{IL}	LOW-level input voltage		-0.5	_	0.3V _{DD}	V
V _{IH}	HIGH-level input voltage		0.7V _{DD}	_	6	V
	LOW lovel output ourrent	V _{OL} = 0.4 V	3	_	_	mA
l _{OL}	LOW-level output current	V _{OL} = 0.6 V	6	_	_	mA
I _{IL}	LOW-level input current	$V_I = V_{SS}$	-10	_	+10	μΑ
I _{IH}	HIGH-level input current	$V_I = V_{DD}$	_	_	+100	μΑ
C _i	Input capacitance	$V_I = V_{SS}$	_	12	13	pF
Select inpu	ts A0 to A1 / INT0 to INT3 / RE	SET				
V_{IL}	LOW-level input voltage		-0.5		+0.3V _{DD}	V
V _{IH}	HIGH-level input voltage		0.7V _{DD}		V _{DD} + 0.5	V
I _{LI}	Input leakage current	pin at V _{DD} or V _{SS}	-1		+50	μΑ
C _i	Input capacitance	$V_I = V_{SS}$	_	1.6	3	pF
Pass Gate						
R _{ON}	Switch resistance	$V_{CC} = 4.5 \text{ V to } 5.5 \text{ V}; V_{O} = 0.4 \text{ V}; I_{O} = 15 \text{ mA}$	4	11	24	Ω
\/	Curitab autaut valtaga	$V_{swin} = V_{DD} = 5.0 \text{ V}; I_{swout} = -100 \mu\text{A}$	_	3.5	_	V
V _{Pass}	Switch output voltage	$V_{swin} = V_{DD} = 4.5 \text{ V to } 5.5 \text{ V; } I_{swout} = -100 \mu\text{A}$	2.6	_	4.5	V
ال	Leakage current	$V_I = V_{DD}$ or V_{SS}	-1	_	+100	μΑ
C _{io}	Input/output capacitance	$V_I = V_{SS}$	_	3	5	pF
INT Output						
I _{OL}	LOW-level output current	V _{OL} = 0.4 V	3	_	_	mA
I _{OH}	HIGH-level output current		_	_	+100	μΑ

4-channel I²C switch with interrupt logic and reset

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AC CHARACTERISTICS

SYMBOL	PARAMETER		RD-MODE -BUS	FAST-I		UNIT
		MIN	MAX	MIN	MAX	7
t _{pd}	Propagation delay from SDA to SD _n or SCL to SC _n	_	0.31	_	0.3 ¹	ns
f _{SCL}	SCL clock frequency	0	100	0	400	kHz
t _{BUF}	Bus free time between a STOP and START condition	4.7	_	1.3	_	μs
t _{HD;STA}	Hold time (repeated) START condition After this period, the first clock pulse is generated	4.0	_	0.6	_	μs
t _{LOW}	LOW period of the SCL clock	4.7	<u> </u>	1.3	_	μs
tHIGH	HIGH period of the SCL clock	4.0	_	0.6	_	μs
t _{SU;STA}	Set-up time for a repeated START condition	4.7	_	0.6	_	μs
t _{SU;STO}	Set-up time for STOP condition	4.0	_	0.6	_	μs
t _{HD;DAT}	Data hold time	0 ²	3.45	02	0.9	μs
t _{SU;DAT}	Data set-up time	250	_	100	_	ns
t _R	Rise time of both SDA and SCL signals	_	1000	$20 + 0.1C_b^3$	300	ns
t _F	Fall time of both SDA and SCL signals	_	300	$20 + 0.1C_b^3$	300	μs
C _b	Capacitive load for each bus line	_	400	_	400	μs
t _{SP}	Pulse width of spikes which must be suppressed by the input filter	_	50		50	ns
t _{VD:DATL}	Data valid (HL)	_	1	_	1	μs
t _{VD:DATH}	Data valid (LH)	_	0.6	_	0.6	μs
t _{VD:ACK}	Data valid Acknowledge	_	1	_	1	μs
ĪNT			-			
t _{iv}	INTn to INT active valid time	_	4	_	4	μs
t _{ir}	INTn to INT inactive delay time	_	2	_	2	μs
L _{pwr}	LOW level pulse width rejection or INTn inputs	1	_	1	_	μs
H _{pwr}	HIGH level pulse width rejection or INTn inputs	0.5		0.5	_	μs
RESET						
t _{WL(rst)}	Pulse width low reset	4	_	4	_	ns
t _{rst}	Reset time (SDA clear)	500	_	500	_	ns
t _{REC:STA}	Recovery to Start	0	_	0	_	ns

NOTES:

- Pass gate propagation delay is calculated from the 20 Ω typical R_{ON} and the 15 pF load capacitance.
 A device must internally provide a hold time of at least 300 ns for the SDA signal (referred to the V_{IH(min)} of the SCL signal) in order to bridge the undefined region of the falling edge of SCL.
- 3. C_b = total capacitance of one bus line in pF.

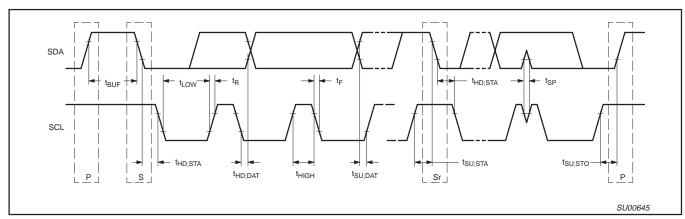


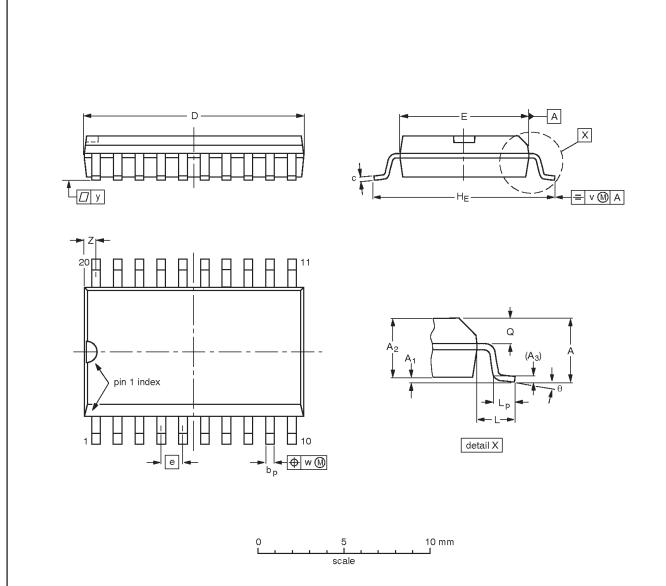
Figure 14. Definition of timing on the I²C-bus

4-channel I²C switch with interrupt logic and reset

PCA9545

SO20: plastic small outline package; 20 leads; body width 7.5 mm

SOT163-1



DIMENSIONS (inch dimensions are derived from the original mm dimensions)

UNIT	A max.	A ₁	A ₂	А3	bp	С	D ⁽¹⁾	E ⁽¹⁾	е	HE	L	Lp	Q	v	w	у	z ⁽¹⁾	θ
mm	2.65	0.3 0.1	2.45 2.25	0.25	0.49 0.36	0.32 0.23	13.0 12.6	7.6 7.4	1.27	10.65 10.00	1.4	1.1 0.4	1.1 1.0	0.25	0.25	0.1	0.9 0.4	8°
inches	0.1	0.012 0.004	0.096 0.089	0.01	0.019 0.014	0.013 0.009	0.51 0.49	0.30 0.29	0.05	0.419 0.394	0.055		0.043 0.039	0.01	0.01	0.004	0.035 0.016	o°

Note

1. Plastic or metal protrusions of 0.15 mm (0.006 inch) maximum per side are not included.

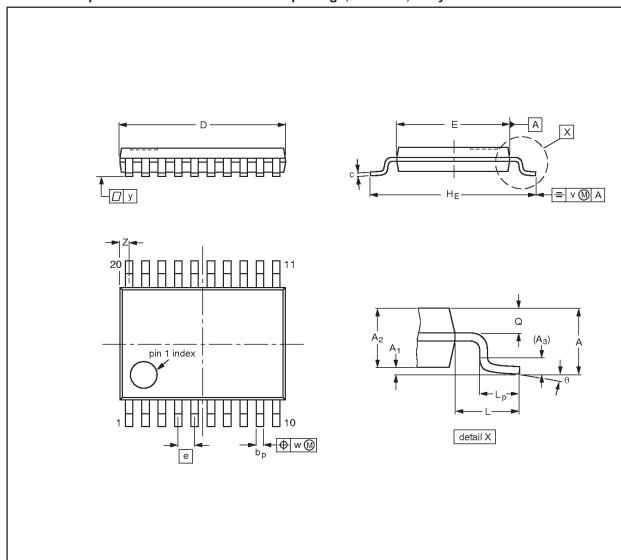
OUTLINE		REFER	EUROPEAN	ISSUE DATE	
VERSION	IEC	JEDEC	JEITA	PROJECTION	ISSUE DATE
SOT163-1	075E04	MS-013			-99-12-27 03-02-19

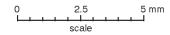
4-channel I²C switch with interrupt logic and reset

PCA9545

TSSOP20: plastic thin shrink small outline package; 20 leads; body width 4.4 mm

SOT360-1





DIMENSIONS (mm are the original dimensions)

UNIT	A max.	A ₁	A ₂	A ₃	bp	O	D ⁽¹⁾	E ⁽²⁾	ψ	HE	L	Lp	œ	٧	w	у	Z ⁽¹⁾	θ
mm	1.1	0.15 0.05	0.95 0.80	0.25	0.30 0.19	0.2 0.1	6.6 6.4	4.5 4.3	0.65	6.6 6.2	1	0.75 0.50	0.4 0.3	0.2	0.13	0.1	0.5 0.2	8° 0°

Notes

- 1. Plastic or metal protrusions of 0.15 mm maximum per side are not included.
- 2. Plastic interlead protrusions of 0.25 mm maximum per side are not included.

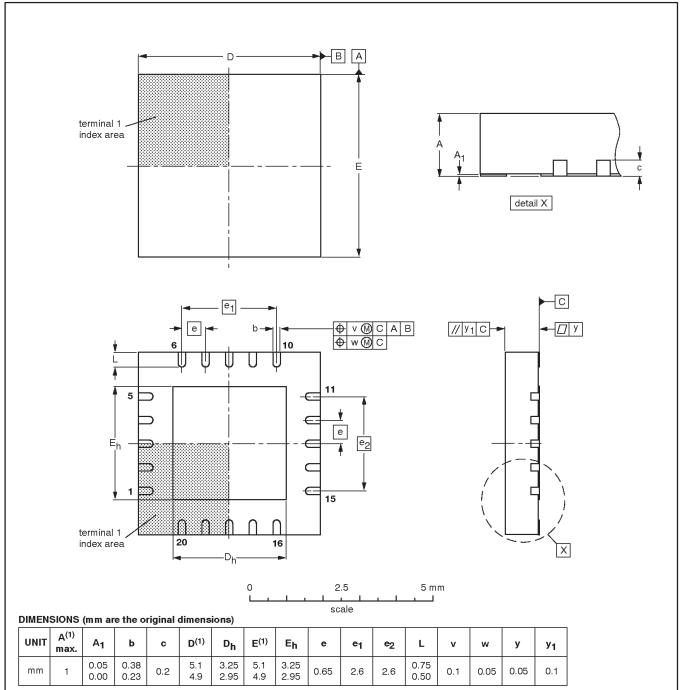
OUTLINE		REFEF	EUROPEAN	ISSUE DATE	
VERSION	IEC	JEDEC	JEITA	PROJECTION	ISSUE DATE
SOT360-1		MO-153			-99-12-27 03-02-19

4-channel I²C switch with interrupt logic and reset

PCA9545

HVQFN20: plastic thermal enhanced very thin quad flat package; no leads; 20 terminals; body $5 \times 5 \times 0.85$ mm

SOT662-1



Note

1. Plastic or metal protrusions of 0.075 mm maximum per side are not included.

0	OUTLINE VERSION		REFER	EUROPEAN	ISSUE DATE		
VI		IEC	JEDEC	JEITA		PROJECTION	ISSUE DATE
S	OT662-1		MO-220				-01-08-08 02-10-22

4-channel I^2C switch with interrupt logic and reset

PCA9545

REVISION HISTORY

Rev	Date	Description
_4	20040929 Product data sheet (9397 750 14114). Supersedes data of 2002 Dec 13 (9397 750 10873).	
		Modifications:
		■ Table 1. "Control Register; Write — Channel Selection / Read — Channel Status" on page 5: add 'No channel selected; power-up/reset default state' row to bottom of table.
_3	20021213	Product data (9397 750 10873); ECN 853-2302 29160 of 06 November 2002.
_2	20020328	Product data (9397 750 09608); ECN 853-2302 27940 of 28 March 2002.

4-channel I²C switch with interrupt logic and reset

PCA9545



Purchase of Philips I²C components conveys a license under the Philips' I²C patent to use the components in the I²C system provided the system conforms to the I²C specifications defined by Philips. This specification can be ordered using the code 9398 393 40011.

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Level	Data sheet status ^[1]	Product status ^[2] [3]	Definitions
I	Objective data sheet	Development	This data sheet contains data from the objective specification for product development. Philips Semiconductors reserves the right to change the specification in any manner without notice.
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- [2] The product status of the device(s) described in this data sheet may have changed since this data sheet was published. The latest information is available on the Internet at URL http://www.semiconductors.philips.com.
- [3] For data sheets describing multiple type numbers, the highest-level product status determines the data sheet status.

Definitions

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Limiting values definition — Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 60134). Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only and operation of the device at these or at any other conditions above those given in the Characteristics sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability.

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Date of release: 09-04

Document number: 9397 750 14114

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